

Lecture 6: Determinants
(book: 3.1, 3.2).

Previous lecture: the inverse of a matrix.

Application of the inverse matrix: Cryptography.

Imitation game. A is used to encrypt the message.

Hill algorithm.

$$A = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix}$$

ATTACK-Now.

$$\begin{bmatrix} A \\ T \end{bmatrix} = \begin{bmatrix} 1 \\ 20 \end{bmatrix}$$

$$\begin{bmatrix} \bar{A} \\ \bar{T} \end{bmatrix} = \begin{bmatrix} 20 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} A \\ \bar{A} \end{bmatrix} \begin{bmatrix} \bar{A} \\ \bar{T} \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 20 \end{bmatrix} = \begin{bmatrix} 41 \\ 61 \end{bmatrix}$$

$$\begin{bmatrix} C \\ K \end{bmatrix} = \begin{bmatrix} 3 \\ 11 \end{bmatrix}$$

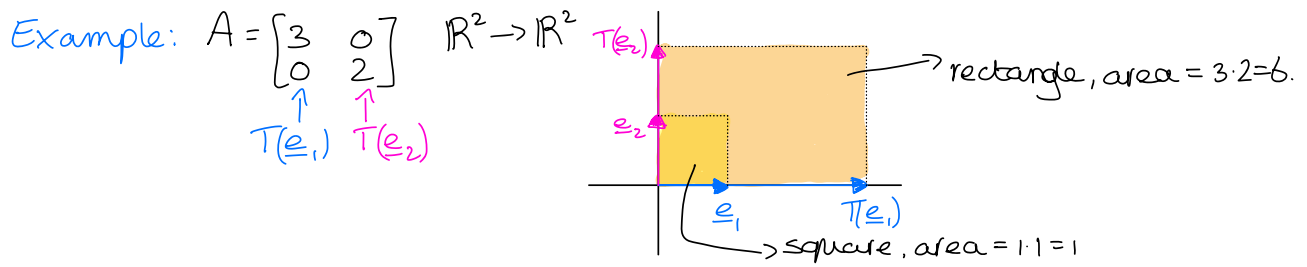
$$\begin{bmatrix} \bar{C} \\ \bar{K} \end{bmatrix} = \begin{bmatrix} 27 \\ 14 \end{bmatrix} \dots$$

$$\begin{bmatrix} A^{-1} \end{bmatrix} \begin{bmatrix} 41 \\ 61 \end{bmatrix} = \begin{bmatrix} 1 \\ 20 \end{bmatrix} = \begin{bmatrix} A \\ T \end{bmatrix}.$$

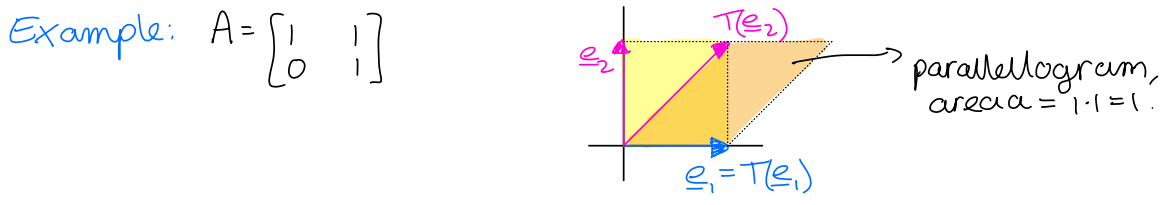
Inverse of a 2×2 matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

* If $ad - bc \neq 0$, then A is invertible and $A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$.
↳ determinant.

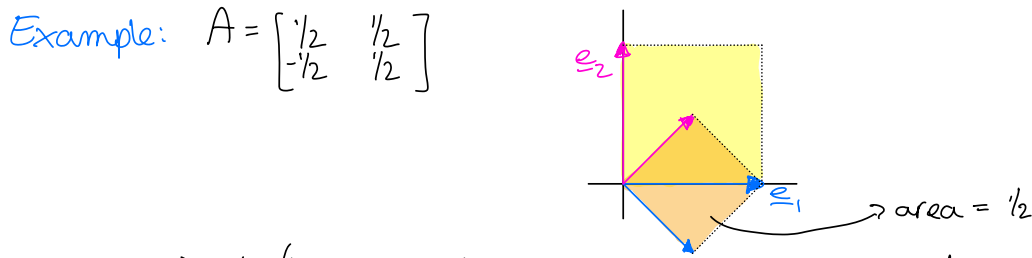
* If $ad - bc = 0$, then A is not invertible
↳ singular.



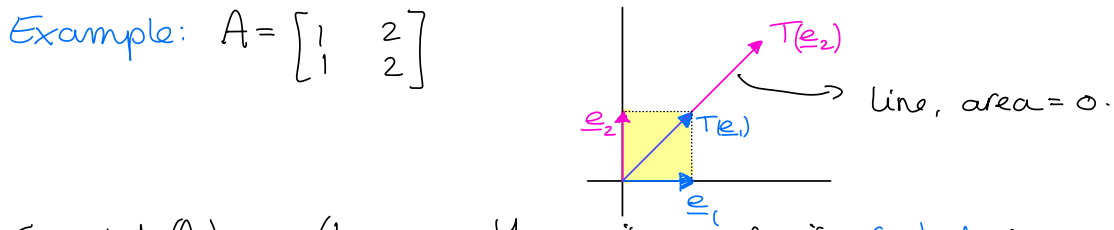
So, A is stretching objects in \mathbb{R}^2 .
 The stretching/scaling factor is $\delta = \det(A)$.
 $\hookrightarrow > 1$ because the area increases.



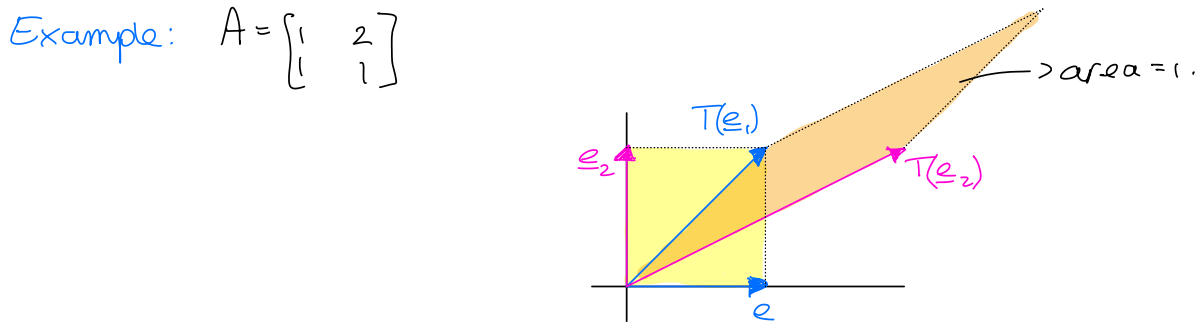
So, $\det(A) = 1$ (because the area stays the same).



So, $\det(A) = 1/2$ (because the area squishes with a factor $1/2$)



So, $\det(A) = 0$ (because the unit square is crushed in a line).



The orientation of space has been "inverted"
 So, $\det(A) = -1$.

The **determinant** of a square ($n \times n$) matrix is a **scalar** associated with the matrix.

Notation: $\det(A)$ $|A|$.

It measures how the transformation $T: \underline{x} \rightarrow A\underline{x}$ "scales" space:
* in \mathbb{R}^2 it measures the change in **areas** of objects by T .
* in \mathbb{R}^3 it measures the change in **volumes** of objects by T .

$\det(A) = 0 \Rightarrow$ spaces are "flattened" / we are losing one dimension
 \Rightarrow range \neq codomain
 \Rightarrow transformation is not surjective (onto).
 \Rightarrow A is **not** invertible.

How to **compute** the **determinant**?

* **Gaussian** elimination.

* **cofactor** expansion.

Recall $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$.

Cofactor expansion for an $n \times n$ matrix:

* Focus on a specific row i or column j .

* For example, for row i :

$$\det(A) = \sum_{j=1}^n a_{ij} \cdot C_{ij}$$

* a_{ij} : entry of A at location (i, j)

* C_{ij} : (i, j) -cofactor = $(-1)^{i+j} \cdot \det(A_{ij})$

* A_{ij} : submatrix obtained by removing row i and column j .

Example $A = \begin{bmatrix} 3 & 5 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix}$

Cofactor expansion across the **first row**

$$\begin{aligned} \det(A) &= 3 \cdot (-1)^{1+1} \cdot \begin{vmatrix} 2 & 1 \\ 0 & 1 \end{vmatrix} + 5 \cdot (-1)^{1+2} \cdot \begin{vmatrix} 0 & 1 \\ 0 & 1 \end{vmatrix} + 1 \cdot (-1)^{1+3} \cdot \begin{vmatrix} 0 & 2 \\ 0 & 0 \end{vmatrix} \\ &= 3 \cdot 2 - 5 \cdot 0 + 1 \cdot 0 = 6. \end{aligned}$$

Cofactor expansion across the **first column**.

$$\det(A) = 3 \cdot (-1)^{1+1} \begin{vmatrix} 2 & 1 \\ 0 & 1 \end{vmatrix} + 0 + 0 = 3 \cdot 2 = 6.$$

So, be **smart**: choose a row/column with **many** 0s.

Triangular matrix: the entries below/above the main diagonal are all 0s.

upper triangular \swarrow \searrow lower triangular.

$$\begin{bmatrix} * & * & * & * \\ 0 & * & * & * \\ 0 & 0 & * & * \\ 0 & 0 & 0 & * \end{bmatrix}$$

$$\begin{bmatrix} * & 0 & 0 & 0 \\ * & * & 0 & 0 \\ * & * & * & 0 \\ * & * & * & * \end{bmatrix}$$

Diagonal matrix: a square matrix whose nondiagonal entries are all 0s.

$$\begin{bmatrix} * & 0 & 0 & 0 \\ 0 & * & 0 & 0 \\ 0 & 0 & * & 0 \\ 0 & 0 & 0 & * \end{bmatrix}$$

For triangular or diagonal matrices, the determinant equals the product of the entries on the main diagonal.

$$\begin{bmatrix} * & * & * & * \\ 0 & * & * & * \\ 0 & 0 & * & * \\ 0 & 0 & 0 & * \end{bmatrix}$$

$$\det(A) = a_{11} \cdot a_{22} \cdot a_{33} \cdot a_{44} \cdot \dots \cdot a_{nn}$$

REF is upper triangular.

So, maybe we can use Gaussian elimination to compute the determinant?

How do row operations change the determinant?

* two rows of A are interchanged to produce B:

$$\det(B) = -\det(A)$$

* one row of A is multiplied by k to produce B:

$$\det(B) = k \cdot \det(A)$$

* a multiple of one row of A is added to another row to produce B: $\det(B) = \det(A)$.

Example: $\begin{vmatrix} 0 & 5 & 1 \\ 4 & -3 & 0 \\ 2 & 4 & 1 \end{vmatrix} \xrightarrow{R_1 \leftrightarrow R_3} -1 \cdot \begin{vmatrix} 2 & 4 & 1 \\ 4 & -3 & 0 \\ 0 & 5 & 1 \end{vmatrix} \xrightarrow{R_2: R_2 - 2 \cdot R_1} \dots$

$$-1 \cdot \begin{vmatrix} 2 & 4 & 1 \\ 0 & -11 & -2 \\ 0 & 5 & 1 \end{vmatrix} \xrightarrow{R_3: R_3 + 5/11 \cdot R_2} -1 \cdot \begin{vmatrix} 2 & 4 & 1 \\ 0 & -11 & -2 \\ 0 & 0 & 11/11 \end{vmatrix} = (-1) \cdot 2 \cdot (-11) \cdot 1/11 = 2$$

square matrix A not invertible

$\Rightarrow A$ is not row equivalent to I_n .

\Rightarrow a pivot is missing.

$\Rightarrow \det(\text{REF of } A) \stackrel{0}{=} 0$

$\Rightarrow \det(A) = (-1)^{\# \text{swaps}} \det(\text{REF of } A) = (-1)^{\# \text{swaps}} \cdot 0 = 0$

$\Rightarrow \det(A) = 0$.

Conclusion: square matrix A is not invertible $\Leftrightarrow \det(A) = 0$.

Properties of determinants:

* $\det(A^T) = \det(A)$

* $\det(AB) = \det(A) \cdot \det(B)$ (Thm 6).

* but $\det(A+B) \neq \det(A) + \det(B)$ in general.

* $\det(c \cdot A) = c^n \cdot \det(A)$

Theorem: $\det(A^{-1}) = \frac{1}{\det(A)}$ (for all invertible matrices).

Proof: $I_n = A \cdot A^{-1}$

$\Rightarrow \det(I_n) = \det(A \cdot A^{-1})$

$\rightarrow 1 = \det(A) \cdot \det(A^{-1})$

$\Rightarrow \frac{1}{\det(A)} = \det(A^{-1}) \quad \square$

Summary (so far):

Let A be an $m \times n$ matrix with columns a_1, a_2, \dots, a_n .

$$m > n: \begin{bmatrix} A \end{bmatrix}$$

The following statements are equivalent:

- ① A has a pivot in every column.
- ② A has n pivot positions.
- ③ There are no free variables.
- ④ $A\underline{x} = \underline{0}$ has only the trivial sol.
- ⑤ $\{a_1, a_2, \dots, a_n\}$ is linearly indep.
- ⑥ $T: \underline{x} \mapsto A\underline{x}$ is one-to-one/injective.

$$m \leq n: \begin{bmatrix} A \end{bmatrix}$$

The following statements are equivalent:

- ⓐ A has a pivot in every row.
- ⓑ A has m pivot positions.
- ⓒ The echelon form of A does not contain a row of all zeros.
- ⓓ $A\underline{x} = \underline{b}$ is consistent for every \underline{b} in \mathbb{R}^m .
- ⓔ $\text{Span}\{a_1, a_2, \dots, a_n\} = \mathbb{R}^m$.
- ⓕ $T: \underline{x} \mapsto A\underline{x}$ is onto/surjective.

The Invertible Matrix Theorem:

If A is square ($n=m$), then statements ② and ⑥ are equivalent. Hence, the following statements are equivalent for square matrices

* ① - ⑥, ⓐ - ⓕ

* A is invertible

* There is a matrix C such that $CA = I_n$ and $AC = I_n$

* A is row equivalent to I_n .

* A^T is invertible.

* $\det A \neq 0$