

Lecture 1: Systems of linear equations, Gaussian elimination.  
(book: 1.1, 1.2)

$x$ : chickens.  
 $y$ : cows.

$$\begin{cases} x+y=30 \\ 2x+4y=74 \end{cases}$$

This is a system of linear equations (SLE)

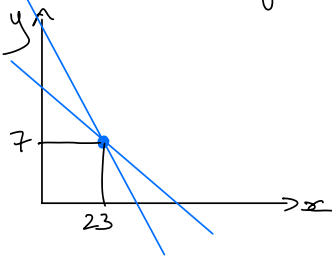
2 equations in 2 variables.

We need a solution (a pair  $(x,y)$ ) that works for both equations.

We have 2 variables, so we "live" in  $\mathbb{R}^2$ .

Each equation of this SLE represents a line in  $\mathbb{R}^2$ .

From a geometric/row point of view: we're looking for an intersection of those two lines.



In general solving an SLE means:

- \*  $\mathbb{R}^2$ : find intersection of lines in a plane.
  - \*  $\mathbb{R}^3$ : " " " planes in a 3d-space.
  - \*  $\mathbb{R}^n$ : " " " hyperplanes in a hyperspace
- } a geometric/row point of view.

$$\begin{cases} x+y=30 \\ 2x+4y=74 \end{cases} \rightarrow \begin{cases} x+y=30 \\ 2x+4y-2 \cdot (x+y)=74-2 \cdot 30 \end{cases} \rightarrow \begin{cases} x+y=30 \\ \frac{1}{2} \cdot 2y = 14 \cdot \frac{1}{2} \end{cases}$$

$$\begin{cases} x+y-y=30-7 \\ y=7 \end{cases} \rightarrow \begin{cases} x=23 \\ y=7 \end{cases}$$

So, the SLE has a solution and solution is unique.

Efficient procedure to solve an SLE: Gaussian elimination/row reduction.

An SLE can be summarized by:

- \* coefficient matrix  $A$
- \* vector  $\underline{b}$  of RHS numbers.

} augmented matrix  $[A \mid \underline{b}]$

$$\begin{cases} x+y=30 \\ 2x+4y=74 \end{cases}$$

$$A = \begin{bmatrix} 1 & 1 \\ 2 & 4 \end{bmatrix}$$

$$\underline{b} = \begin{bmatrix} 30 \\ 74 \end{bmatrix}$$

$$\left[ \begin{array}{cc|c} 1 & 1 & 30 \\ 2 & 4 & 74 \end{array} \right]$$

2x2 matrix  
# rows x # columns.  
# equations x # variables.  
 $m \times n$

$$[A; \underline{b}] = \left[ \begin{array}{cc|c} 1 & 1 & 30 \\ 2 & 4 & 74 \end{array} \right] \xrightarrow{R_2: R_2 - 2 \cdot R_1} \left[ \begin{array}{cc|c} 1 & 1 & 30 \\ 0 & 2 & 14 \end{array} \right] \xrightarrow{R_2: R_2 * 1/2} \left[ \begin{array}{cc|c} 1 & 1 & 30 \\ 0 & 1 & 7 \end{array} \right]$$

$$\xrightarrow{R_1: R_1 - R_2} \left[ \begin{array}{cc|c} 1 & 0 & 23 \\ 0 & 1 & 7 \end{array} \right] \quad \begin{cases} 1 \cdot x + 0 \cdot y = 23 \\ 0 \cdot x + 1 \cdot y = 7 \end{cases} \quad \begin{cases} x = 23 \\ y = 7 \end{cases}$$

So, the unique solution is  $\begin{cases} x = 23 \\ y = 7 \end{cases}$

The corresponding SLEs of these augmented matrices are all equivalent ( $\sim$ ) to each other: they share the same solution set.

---

Two matrices are row equivalent if one matrix can be changed into the other by means of a row operation:

- ① Replacement: add a scalar multiple of a row to another row.
- ② Scaling: multiply a row by a nonzero scalar.
- ③ Interchange: swap two rows.

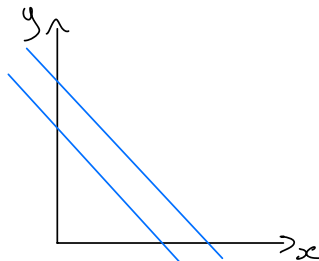
If the augmented matrices of two SLEs are row equivalent, then the two SLEs are equivalent.

An SLE can have:

- \* one **unique** solution
- \* **infinitely** many solutions
- \* **no** solution

} SLE is **consistent**  
 } SLE is **inconsistent**.

$$\begin{cases} x+y=30 \\ x+y=49 \end{cases}$$

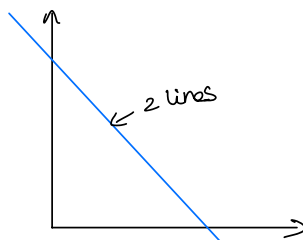


two parallel lines  
 → no intersection  
 → no solution  
 → SLE is **inconsistent**.

$$\left[ \begin{array}{cc|c} 1 & 1 & 30 \\ 1 & 1 & 49 \end{array} \right] \xrightarrow{R_2: R_2 - R_1} \left[ \begin{array}{cc|c} 1 & 1 & 30 \\ 0 & 0 & 19 \end{array} \right] \quad 0=19 \quad \downarrow$$

such a row  $[0 \ 0 \ \dots \ 0 \ | \ \alpha]$ ,  $\alpha \neq 0$ , is typical for an inconsistent SLE.

$$\begin{cases} x+y=30 \\ 2x+2y=60 \end{cases}$$



they are the same line  
 → infinitely many points of intersection  
 → **infinitely** many solutions.

$$\left[ \begin{array}{cc|c} 1 & 1 & 30 \\ 2 & 2 & 60 \end{array} \right] \xrightarrow{R_2: R_2 - 2R_1} \left[ \begin{array}{cc|c} 1 & 1 & 30 \\ 0 & 0 & 0 \end{array} \right] \quad \begin{cases} x+y=30 \\ 0=0 \end{cases}$$

$\begin{matrix} \text{basic var} & & \text{free var} \\ \uparrow & & \uparrow \\ \textcircled{1} & 1 & \vdots \end{matrix}$

Solution set in **parametric form**  $\begin{cases} x = 30 - y \\ y \text{ is free} \end{cases}$

$y$  is a **free variable** (we can choose any value we want)  
 $x$  is a **basic variable** (we cannot choose it)

Note: having a zero does not necessarily mean that there are infinitely many solutions.

For example:  $\left[ \begin{array}{cc|c} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right] \quad \begin{cases} x=1 \\ y=0 \end{cases}$  So, the SLE has a unique sol.

Let's formalize the row reduction / Gaussian elimination algorithm:

**pivot (leading entry):**  
leftmost nonzero element in a row

Row echelon form (REF): (not unique for a matrix)

$$\begin{bmatrix} -2 & 1 & 0 & 3 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & -4 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

one unique sol.

or

$$\begin{bmatrix} 2 & -3 & 2 & 1 \\ 0 & 0 & 4 & 8 \\ 0 & 0 & 0 & 5 \end{bmatrix}$$

no solution (because there is a pivot in the last column).

- ① All non zero rows are above any zero row.
- ② Every pivot in a row is in a column to the right of the pivot of the row above it.
- ③ All entries below a pivot are zero.

It tells you:

- \* whether there is a solution (existence question)
  - is there a row  $[0 \dots 0 \mid a]$  with  $a \neq 0$ ? (last column is a pivot column)
- \* whether the solution is unique (uniqueness question)
  - are there free variables?
  - are all variables basic variables?
  - does every column in the coefficient matrix have a pivot?

Reduced row echelon form (RREF): (unique for a matrix).

$$\begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \end{bmatrix} \quad \begin{cases} x_1 = 2 \\ x_2 = 0 \\ x_3 = -1 \end{cases}$$

or

$$\begin{bmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{cases} x_1 = -1 - x_3 \\ x_2 = -2 \\ x_3 \text{ is free} \end{cases}$$

- ④ All pivots are equal to 1.
- ⑤ Each pivot is the only nonzero entry in its column.

It tells you:

- \* the solution.

Example (Gaussian elimination algorithm):

$$\begin{cases} 2x_2 - 8x_3 = 8 \\ x_1 - 2x_2 + x_3 = 0 \\ -4x_1 + 5x_2 + 9x_3 = -9 \end{cases}$$

$$\left[ \begin{array}{ccc|c} 0 & 2 & -8 & 8 \\ -4 & -2 & 1 & 0 \\ -4 & 5 & 9 & -9 \end{array} \right] \sim R_1 \leftrightarrow R_2$$

$$\left[ \begin{array}{ccc|c} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ -4 & 5 & 9 & -9 \end{array} \right] \sim R_3: R_3 + 4 \cdot R_1$$

$$\left[ \begin{array}{ccc|c} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ 0 & -3 & 13 & -9 \end{array} \right] \sim R_3: R_3 + \frac{3}{2} R_2$$

$$\left[ \begin{array}{ccc|c} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ 0 & 0 & 1 & 3 \end{array} \right] \sim \begin{array}{l} R_1: R_1 - R_3 \\ R_2: R_2 + 8R_3 \end{array}$$

echelon form!  
the SLE is consistent  
the solution is unique.

$$\left[ \begin{array}{ccc|c} 1 & -2 & 0 & -3 \\ 0 & 2 & 0 & 32 \\ 0 & 0 & 1 & 3 \end{array} \right] \sim R_2: R_2 \cdot \frac{1}{2}$$

$$\left[ \begin{array}{ccc|c} 1 & -2 & 0 & -3 \\ 0 & 1 & 0 & 16 \\ 0 & 0 & 1 & 3 \end{array} \right] \sim R_1: R_1 + 2 \cdot R_2$$

$$\left[ \begin{array}{ccc|c} 1 & 0 & 0 & 29 \\ 0 & 1 & 0 & 16 \\ 0 & 0 & 1 & 3 \end{array} \right]$$

reduced echelon form!

$$\begin{cases} x_1 = 29 \\ x_2 = 16 \\ x_3 = 3 \end{cases}$$